

HW #5

7.6

Assume $T = 300\text{K}$ and $M = 22\text{ AMU}$, $1.0\text{ AMU} = 1.67 \times 10^{-27}\text{ kg}$;

$$\Delta v_D = (8kT \ln 2 / Mc^2)^{1/2} v_0 = 3.17 \times 10^{-6} v_0$$

λ	v_0	Δv_D	$\Delta \lambda_D$
6328 Å	4.74^{14} Hz	1.5 GHz	0.02 Å
1.1523 μm	2.6^{14}	0.823	0.0365 Å
3.39 μm	8.85^{13}	0.28	0.107 Å

7.10

This is a reasonable model for the pulsed N_2 laser which has a very high gain and lases at 0.337 μm . Its major drawback is that it is self-terminating because the inversion can not be maintained indefinitely – fact that comes out of the analysis that follows.

$$\frac{dN_2}{dt} = P_2 - \frac{N_2}{\tau_2} \quad \text{whose solution is: } N_2(t) = P_2 \tau_2 (1 - \exp[-t/\tau_2])$$

$$\frac{dN_1}{dt} = + \frac{N_2}{\tau_2} - \frac{N_1}{\tau_1} \quad \text{or} \quad \frac{dN_1}{dt} + \frac{N_1}{\tau_1} = P_2 (1 - \exp[-t/\tau_2])$$

$$N_1 = P_2 \tau_1 \left\{ 1 - \frac{\tau_1/\tau_2}{\tau_1/\tau_2 - 1} e^{-t/\tau_1} + \frac{1}{\tau_1/\tau_2 - 1} e^{-t/\tau_2} \right\}$$

It is informative to consider the steady-state populations, i.e., where $t \gg \tau_{2,1}$. $N_2(t \rightarrow \infty) = P_2 \tau_2$ and $N_1(t \rightarrow \infty) = P_2 \tau_1$. Note that since $\tau_1 > \tau_2$, we have the undesirable situation of $N_1 > N_2$ which means that the system will not lase in a steady state. However, one can obtain a transient inversion (and a laser) as the sketch below indicates.

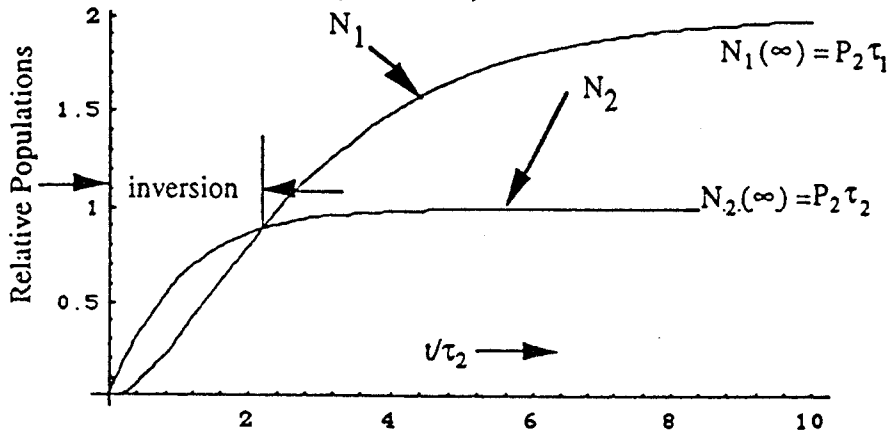


Figure for problem 7.10

$$N_2(t \rightarrow \infty) = 10^{20} \times 10^{-6} = 10^{14} \text{ cm}^{-3}, \quad N_1(t \rightarrow \infty) = 10^{20} \times 2 \times 10^{-6} = 2 \times 10^{14} \text{ cm}^{-3}$$

$$\text{Let } t/\tau_1 = x; \quad (\tau_1/\tau_2) = 2; \quad N_1 = N_2 \text{ when } 2(1 - 2e^{-x} + e^{-2x}) = (1 - e^{-2x});$$

$$\text{Collect terms, multiply by } e^{2x} \text{ and factor: } f(x) = [e^x - 3][e^x - 1] = 0;$$

$$\text{where } x = t/\tau_1; \quad F(x) = 0 \text{ at } x=0 \text{ (i.e. at the start) or } x = t/\tau_1 = \ln 3: \therefore t = 1.0986 \tau_1 = 2.2 \text{ μsec}$$